Stochastic Processes

Midterm 1 9:00 a.m. - 11:30 a.m., 10/27/08

IMPORTANT:

- Remember to write down your i.d. number and your name.
- There are 4 problem sets with <u>110</u> points in total.
- Show all your work with detailed explanations. Correct answers *without* any explanations will carry NO credits. However, wrong answers with correct reasonings will get partial credits.

You may need the following formulas:

• Let $\mathbf{x} = [X_1, X_2, \cdots, X_n]$ be a real Gaussian random vector with mean vector \mathbf{m}_x and covariance matrix \mathbf{K}_x . Then, the joint pdf $f_{\mathbf{x}}(\boldsymbol{x})$ is given by

$$f_{\mathbf{x}}(\boldsymbol{x}) = \frac{1}{(2\pi)^{n/2} \det(\mathbf{K}_x)^{1/2}} \exp\left(-\frac{1}{2}(\boldsymbol{x} - \mathbf{m}_x)^T \mathbf{K}_x^{-1}(\boldsymbol{x} - \mathbf{m}_x)\right).$$

• Consider a jointly Gaussian random vector $[\mathbf{x}^T \ \mathbf{y}^T]^T$ with $\mathbf{x} \sim \mathcal{N}(\mathbf{m}_{\mathbf{x}}, \mathbf{K}_{\mathbf{x}})$ and $\mathbf{y} \sim \mathcal{N}(\mathbf{m}_{\mathbf{y}}, \mathbf{K}_{\mathbf{y}})$. Then, the conditional density $f_{\mathbf{x}|\mathbf{y}}(\mathbf{x}|\mathbf{y})$ also follows a joint Gaussian density with

$$\mathbf{x}|\mathbf{y} \sim \mathcal{N}\Big(\mathbf{m_x} + \mathbf{K_{xy}K_y}^{-1}(\mathbf{y} - \mathbf{m_y}), \mathbf{K_x} - \mathbf{K_{xy}K_y}^{-1}\mathbf{K_{yx}}\Big)$$

where $\mathbf{K}_{\mathbf{x}\mathbf{y}} = E\left[(\mathbf{x} - \mathbf{m}_{\mathbf{x}})(\mathbf{y} - \mathbf{m}_{\mathbf{y}})^{H}\right]$ and $\mathbf{K}_{\mathbf{y}\mathbf{x}} = \mathbf{K}_{\mathbf{x}\mathbf{y}}^{H}$

• The correlation coefficient ρ between random variables X and Y is defined by

$$\rho \triangleq \frac{E[(X - \mu_X)(Y - \mu_Y)]}{\sigma_X \sigma_Y},$$

where $\mu_X = E[X]$, $\mu_Y = E[Y]$, $\sigma_X^2 = \operatorname{Var}(X)$, and $\sigma_Y^2 = \operatorname{Var}(Y)$.

1. (15 points)

Jointly Gaussian implies marginal Gaussian, but the converse is not necessarily true. Please explain this statement, and justify it.

2. (10+10=20 points)

Let X and Y be i.i.d. standard Gaussian random variables.

- (a) Show that X + Y and X Y are independent.
- (b) Find $E[X^3 Y^3|X Y]$. (Hint: Use part (a).)

3. $(10 \text{ points} \times 5 = 50 \text{ points})$

Let $\mathbf{w} = [X, Y, Z]^T \sim \mathcal{N}(\mathbf{m}_w, \mathbf{K}_w)$, where $\mathbf{m}_w = [1 \ 2 \ 0]^T$ and the covariance matrix \mathbf{K}_w is

$$\mathbf{K}_{\mathsf{w}} = \begin{bmatrix} 3 & 1 & 1 \\ 1 & 3 & 0 \\ 1 & 0 & 1 \end{bmatrix}$$

- (a) Find α such that $X + \alpha Z$ and Z are independent.
- (b) Find the probability density function (pdf) for S = X + Y + Z.
- (c) Find the conditional variance Var(X|Y, Z).
- (d) Find the correlation coefficient ρ_{xy} between X and Y.
- (e) Let $\mathbf{r} = [X, Z]^T$. Find **A** and **b** such that the linear transformation $\mathbf{Ar} + \mathbf{b}$ is a Gaussian random vector with uncorrelated components, each with zero mean and unit variance.

4. (10+15=25 points)

Consider a communication system that is corrupted by unknown interferece Z and Gaussian noise W. Mathematically, the received signal Y can be modeled as

$$Y = X + Z + W,$$

where X is the desired signal equally likely to 1 or -1, and $W \sim \mathcal{N}(0, \sigma^2)$. We are given that E[Z] = 0 and $\operatorname{Var}(Z) = A^2$, but the exact statistical distribution of Z is not known. Assume X, Z, W are mutually independent.

- (a) Suppose we model Z as a Gaussian random variable. Find the posterior probability P[X = 1|Y = y].
- (b) Suppose now Z is modeled as a binary discrete random variable equally likely to be A or -A. Again, find the posterior probability P[X = 1|Y = y].