

Stochastic Processes

Midterm 2

Solutions

1. Bayes Detection (10+10=20 points)

- (a) Suppose the state of nature is $\Omega = \{x_1, \dots, x_N\}$. The MAP decision rule based on the observation $Y = y$ is given by

$$\begin{aligned}\hat{X}_{\text{MAP}} &= \arg \max_{x_j} P[X = x_j \mid Y = y] \\ &= \arg \max_{x_j} f_Y(y \mid X = x_j) P[X = x_j].\end{aligned}$$

When $c_{i,j} = 1 - \delta_{i,j}$, the average cost is

$$\begin{aligned}C(D) &\triangleq E[C] \\ &= \sum_i \sum_j c_{i,j} P[\text{decide } H_i \text{ and } H_j \text{ is true}] \\ &= \sum_i \sum_j (1 - \delta_{i,j}) P[\text{decide } H_i \text{ and } H_j \text{ is true}] \\ &= \sum_{i \neq j} P[\text{decide } H_i \text{ and } H_j \text{ is true}],\end{aligned}$$

which is exactly the probability of decision error. Bayes detection rule guarantees that this decision error probability is minimized.

- (b) The maximum likelihood detection rules states

$$L(H_1) \underset{H_2}{\overset{H_1}{\geq}} L(H_2),$$

where $L(H_1)$ and $L(H_2)$ are the likelihood of the signal \mathbf{s} associated with hypothesis H_1 and H_2 , respectively. More specifically, by taking natural log of both sides, we have

$$-\frac{1}{2}(\mathbf{y} - \mathbf{s})^H \mathbf{K}_n^{-1}(\mathbf{y} - \mathbf{s}) \underset{H_2}{\overset{H_1}{\geq}} -\frac{1}{2}\mathbf{y}^H \mathbf{K}_n^{-1}\mathbf{y}.$$

With rearrangement, it follows that

$$\underbrace{\mathbf{s}^H \mathbf{K}_n^{-1} \cdot \mathbf{y}}_{=\mathbf{w}_{\text{ML}}^H} \underset{H_2}{\overset{H_1}{\geq}} \frac{\mathbf{s}^H \mathbf{K}_n^{-1} \mathbf{s}}{2}.$$

That is we can write the ML decision rule as

$$\mathbf{w}_{\text{ML}}^H \cdot \mathbf{y} \underset{H_2}{\overset{H_1}{\geq}} \eta,$$

where

$$\mathbf{w}_{\text{ML}} = \mathbf{K}_n^{-1} \mathbf{s} \quad \text{and} \quad \eta = \frac{\mathbf{s}^H \mathbf{K}_n^{-1} \mathbf{s}}{2}.$$

2. **Estimation** (10 + 5 + 5 = 20 points)

Consider the linear model

$$\mathbf{y} = \mathbf{H}\mathbf{x} + \mathbf{w},$$

where \mathbf{H} is a known $m \times n$ observation matrix, \mathbf{x} is an $n \times 1$ unknown parameter, and \mathbf{w} is a Gaussian noise vector with $\mathbf{w} \sim \mathcal{N}(0, \sigma^2 \mathbf{I})$. Assume \mathbf{H} is full rank.

- (a) Let's consider a more general case for $\mathbf{w} \sim \mathcal{N}(0, \mathbf{K})$ in the proof, where \mathbf{K} is the covariance matrix of \mathbf{w} that is not necessarily diagonal. The situation in this problem is just a special case that $\mathbf{K} = \sigma^2 \mathbf{I}$. So if $\mathbf{w} \sim \mathcal{N}(0, \mathbf{K})$, the ML linear transformation matrix is

$$\mathbf{T}_{ML} = (\mathbf{H}^T \mathbf{K}^{-1} \mathbf{H})^{-1} \mathbf{H}^T \mathbf{K}^{-1}.$$

Let \mathbf{K}_1 and \mathbf{K}_2 be the covariance matrices of $\hat{\mathbf{x}}_{ML}$ and any other linear unbiased estimator $\hat{\mathbf{x}} = \mathbf{T} \cdot \mathbf{y}$, respectively. Therefore, this problem requires you to show that $\mathbf{K}_2 - \mathbf{K}_1$ is p.s.d., i.e.

$$\boldsymbol{\alpha}^T (\mathbf{K}_2 - \mathbf{K}_1) \boldsymbol{\alpha} \geq 0, \quad \forall \boldsymbol{\alpha}. \quad (1)$$

The key steps have two:

→ Any covariance matrix \mathbf{K} is p.s.d. (see topic2)

→ $\mathbf{TH} = \mathbf{I}$ for any linear unbiased estimator $\hat{\mathbf{x}} = \mathbf{T} \cdot \mathbf{y}$ in the linear model $\mathbf{y} = \mathbf{H}\mathbf{x} + \mathbf{w}$.

This can easily be shown that for $E[\hat{\mathbf{x}}] = E[\mathbf{T} \cdot \mathbf{y}] = \mathbf{TH}\mathbf{x} = \mathbf{x}$, we must have $\mathbf{TH} = \mathbf{I}$.

We will use these two facts later in the proof.

So, our objective is to show (1) is true. Carrying out the covariance matrices \mathbf{K}_1 and \mathbf{K}_2 , we have

$$\begin{aligned} \mathbf{K}_1 &= \mathbf{T}_{ML} \mathbf{K} \mathbf{T}_{ML}^T, \\ \mathbf{K}_2 &= \mathbf{T} \mathbf{K} \mathbf{T}^T. \end{aligned}$$

It follows

$$\mathbf{K}_2 - \mathbf{K}_1 = \mathbf{T} \mathbf{K} \mathbf{T}^T - \mathbf{T}_{ML} \mathbf{K} \mathbf{T}_{ML}^T.$$

Next we can conjecture that

$$\mathbf{K}_2 - \mathbf{K}_1 = (\mathbf{T} - \mathbf{T}_{ML}) \mathbf{K} (\mathbf{T} - \mathbf{T}_{ML})^T. \quad (2)$$

If this is the case, then by the fact that \mathbf{K} is p.s.d., we know that

$$\begin{aligned} \boldsymbol{\alpha}^T (\mathbf{K}_2 - \mathbf{K}_1) \boldsymbol{\alpha} &= \underbrace{\boldsymbol{\alpha}^T (\mathbf{T} - \mathbf{T}_{ML})}_{\boldsymbol{\beta}^T} \mathbf{K} \underbrace{(\mathbf{T} - \mathbf{T}_{ML})^T}_{\boldsymbol{\beta}} \boldsymbol{\alpha} \\ &= \boldsymbol{\beta}^T \mathbf{K} \boldsymbol{\beta} \geq 0, \end{aligned}$$

which reaches our objective in (1).

So, now the question is whether or not (2) is true.

Expanding (2) gives

$$\mathbf{T} \mathbf{K} \mathbf{T}^T - \mathbf{T}_{ML} \mathbf{K} \mathbf{T}^T - \mathbf{T} \mathbf{K} \mathbf{T}_{ML}^T + \mathbf{T}_{ML} \mathbf{K} \mathbf{T}_{ML}^T, \quad (3)$$

where

$$\begin{aligned}
\mathbf{T}_{ML}\mathbf{K}\mathbf{T}^T &= (\mathbf{H}^T\mathbf{K}^{-1}\mathbf{H})^{-1}\mathbf{H}^T\mathbf{K}^{-1}\mathbf{K}\mathbf{T}^T \\
&= (\mathbf{H}^T\mathbf{K}^{-1}\mathbf{H})^{-1} \quad (\text{we use } \mathbf{TH}=\mathbf{I} \text{ in this equality}) \\
\mathbf{T}_{ML}\mathbf{K}\mathbf{T}_{ML}^T &= (\mathbf{H}^T\mathbf{K}^{-1}\mathbf{H})^{-1}\mathbf{H}^T\mathbf{K}^{-1}\mathbf{K}\mathbf{K}^{-1}\mathbf{H}(\mathbf{H}^T\mathbf{K}^{-1}\mathbf{H})^{-1} \\
&= (\mathbf{H}^T\mathbf{K}^{-1}\mathbf{H})^{-1}.
\end{aligned}$$

Thus, we see the last 3 terms in (3) are identical. It follows that

$$\begin{aligned}
(\mathbf{T} - \mathbf{T}_{ML})\mathbf{K}(\mathbf{T} - \mathbf{T}_{ML})^T &= \mathbf{T}\mathbf{K}\mathbf{T}^T - \mathbf{T}_{ML}\mathbf{K}\mathbf{T}^T - \mathbf{T}\mathbf{K}\mathbf{T}_{ML}^T + \mathbf{T}_{ML}\mathbf{K}\mathbf{T}_{ML}^T \\
&= \mathbf{T}\mathbf{K}\mathbf{T}^T - \mathbf{T}_{ML}\mathbf{K}\mathbf{T}_{ML}^T \\
&= \mathbf{K}_2 - \mathbf{K}_1.
\end{aligned}$$

This completes the proof.

- (b) Since $\mathbf{K}_2 - \mathbf{K}_1$ is p.s.d., it's diagonal term is non-negative. This is because that, if we choose the vector

$$\boldsymbol{\alpha} = [0, \dots, 0, \underbrace{1}_{i\text{th position}}, 0, \dots, 0]^T,$$

the vector with a '1' in the i th position and zero in others, then

$$\boldsymbol{\alpha}^T(\mathbf{K}_2 - \mathbf{K}_1)\boldsymbol{\alpha} = (\mathbf{K}_2 - \mathbf{K}_1)_{ii} \geq 0, \quad (4)$$

where $(\mathbf{K}_2 - \mathbf{K}_1)_{ii}$ is the i th diagonal term in $\mathbf{K}_2 - \mathbf{K}_1$.

Since $(\mathbf{K}_2 - \mathbf{K}_1)_{ii} = (\mathbf{K}_2)_{ii} - (\mathbf{K}_1)_{ii}$, and the i th diagonal term of \mathbf{K}_2 and \mathbf{K}_1 is the variance of the i th component of $\hat{\mathbf{x}}$ and $\hat{\mathbf{x}}_{ML}$, respectively. It follows from (4) that

$$(\mathbf{K}_2 - \mathbf{K}_1)_{ii} = (\mathbf{K}_2)_{ii} - (\mathbf{K}_1)_{ii} \geq 0.$$

So the variance of the i th component of $\hat{\mathbf{x}}$ is greater than or equal to that of $\hat{\mathbf{x}}_{ML}$.

- (c) The least squares estimator is defined as

$$\hat{\mathbf{x}}_{LS} = \arg \min_{\mathbf{x}} \|\mathbf{y} - \mathbf{H}\mathbf{x}\|^2.$$

This is equivalent to finding a vector $\mathbf{H}\hat{\mathbf{x}}_{LS}$ in the column space of \mathbf{H} that is closest to \mathbf{y} . Thus, $\mathbf{H}\hat{\mathbf{x}}_{LS}$ is the orthogonal projection of \mathbf{y} onto the space spanned by the columns of \mathbf{H} .

Geometrically, we see $\mathbf{y} - \mathbf{H}\hat{\mathbf{x}}_{LS}$ will be orthogonal to $\mathbf{H}\mathbf{x}$ for all \mathbf{x} . Mathematically, this is

$$(\mathbf{H}\mathbf{x})^T(\mathbf{y} - \mathbf{H}\hat{\mathbf{x}}_{LS}) = 0 \quad \text{for all } \mathbf{x}.$$

This leads to the normal equation

$$\mathbf{H}^T(\mathbf{y} - \mathbf{H}\hat{\mathbf{x}}_{LS}) = 0$$

3. Conditional Expectation of Jointly Gaussian (10+10=20 points)

(a) The cross-covariance matrix $\mathbf{K}_{y\hat{z}} = E[(\mathbf{y} - \mathbf{m}_y)(\hat{\mathbf{z}} - E[\hat{\mathbf{z}}])^T]$ can be obtained as

$$\begin{aligned}\mathbf{K}_{y\hat{z}} &= E[(\mathbf{y} - \mathbf{m}_y)(\hat{\mathbf{z}} - E[\hat{\mathbf{z}}])^T] \\ &= E[(\mathbf{y} - \mathbf{m}_y)\hat{\mathbf{z}}^T] \\ &= E[\mathbf{y}\hat{\mathbf{z}}^T] \quad (\text{since } E[\hat{\mathbf{z}}] = 0) \\ &= E[\mathbf{y}\mathbf{z}^T] - E[\mathbf{y}E[\mathbf{z}^T|\mathbf{y}]] \\ &= E[\mathbf{y}\mathbf{z}^T] - E[E[\mathbf{y}\mathbf{z}^T|\mathbf{y}]] \\ &= E[\mathbf{y}\mathbf{z}^T] - E[\mathbf{y}\mathbf{z}^T] \\ &= \mathbf{0}.\end{aligned}$$

(b) (Not graded) See hw2 solutions.

4. Gaussian Sample ($10 \times 5 = 50$ points)

(a) First, it is clear to see $E[\bar{X}_n] = \frac{1}{n} \sum_{i=1}^n E[X_i] = \mu$.

Second, we can use Chebyshev inequality to examine consistency of any unbiased estimators. Here, we have

$$P[|\bar{X}_n - \mu| > k] \leq \frac{\text{Var}(\bar{X}_n)}{k^2}, \quad \text{for any } k > 0. \quad (5)$$

The variance of the sample mean is

$$\begin{aligned}\text{Var}(\bar{X}_n) &= \text{Var}\left(\frac{1}{n} \sum_{i=1}^n X_i\right) = \frac{1}{n^2} \text{Var}\left(\sum_{i=1}^n X_i\right) \\ &= \frac{1}{n^2} \sum_{i=1}^n \text{Var}(X_i) = \frac{1}{n} \sigma^2.\end{aligned}$$

Therefore, by plugging the above result into (5), we can easily show the consistency of sample mean, i.e. for any $k > 0$,

$$\lim_{n \rightarrow \infty} P[|\bar{X}_n - \mu| > k] = 0.$$

(b) The mean and variance are both unknown. We need simultaneously find their ML estimator jointly. That is the vector of parameter to be estimated is $\boldsymbol{\theta} = [\mu, \sigma^2]^T$.

The likelihood function of $\boldsymbol{\theta}$ given $\mathbf{x} = [X_1 = x_1, X_2 = x_2, \dots, X_n = x_n]$ is

$$\begin{aligned}L(\boldsymbol{\theta}|\mathbf{x}) &= f_{\mathbf{x}}(\mathbf{x}; \boldsymbol{\theta}) = \prod_{i=1}^n f_{X_i}(x_i; \boldsymbol{\theta}) \\ &= \frac{1}{(2\pi\sigma^2)^{n/2}} \exp\left(-\frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \mu)^2\right).\end{aligned}$$

And, the log likelihood function is

$$\log L(\boldsymbol{\theta}|\mathbf{x}) = -\frac{n}{2} \log(2\pi\sigma^2) - \frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \mu)^2.$$

Taking partial derivative and solving the following equations simultaneously gives us possible candidates of the ML estimators. It follows that

$$\begin{aligned}\frac{\partial \log L(\theta|\mathbf{x})}{\partial \mu} = 0 &\longrightarrow \hat{\mu}_{ML} = \frac{1}{n} \sum_{i=1}^n X_i = \bar{X}_n, \\ \frac{\partial \log L(\theta|\mathbf{x})}{\partial \sigma^2} = 0 &\longrightarrow \hat{\sigma}_{ML}^2 = \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X}_n)^2,\end{aligned}$$

which are indeed the ML estimators after checking with the boundaries.

So, the answer to this problem is

$$\hat{\sigma}_{ML}^2 = \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X}_n)^2.$$

(c) We see the relation between $\hat{\sigma}_{ML}^2$ and S_n^2 is given by

$$\hat{\sigma}_{ML}^2 = \frac{n-1}{n} S_n^2.$$

And, since S_n^2 is unbiased, we thus conclude $\hat{\sigma}_{ML}^2$ is not unbiased.

(d) The MSE between $\hat{\sigma}_{ML}^2$ and σ^2 is

$$\begin{aligned}E[(\hat{\sigma}_{ML}^2 - \sigma^2)^2] &= E\left[\left(\frac{n-1}{n} S_n^2 - \sigma^2\right)^2\right] \\ &= E\left[\left(\left(\frac{n-1}{n} S_n^2 - \frac{n-1}{n} \sigma^2\right) - \frac{1}{n} \sigma^2\right)^2\right] \\ &= E\left[\left(\frac{n-1}{n} S_n^2 - \frac{n-1}{n} \sigma^2\right)^2\right] + \left(\frac{1}{n} \sigma^2\right)^2 \\ &= \left(\frac{n-1}{n}\right)^2 \text{Var}(S_n^2) + \left(\frac{1}{n} \sigma^2\right)^2 \\ &= \frac{2n-1}{n^2} \sigma^4.\end{aligned}$$

With a little more algebraic efforts, it is not difficult to see with positive integer n

$$\frac{2n-1}{n^2} \sigma^4 < \text{Var}(S_n^2) = \frac{2\sigma^4}{n-1}.$$

This means the ML estimator of σ^2 is more accurate in terms of MSE than the sample variance estimator, although MLE is not unbiased.

(e) We know

$$\begin{aligned}1 - 2F_{T_{n-1}}(-z) &= P\left[-z \leq \frac{\bar{X}_n - \mu}{S_n/\sqrt{n}} \leq z\right] \\ &= P\left[\bar{X}_n - \frac{S_n z}{\sqrt{n}} \leq \mu \leq \bar{X}_n + \frac{S_n z}{\sqrt{n}}\right] \\ &= 1 - \alpha.\end{aligned}$$

For $1 - \alpha = 0.95$, we need $F_{T_{n-1}}(-z) = 0.025$, where $F_{T_{n-1}}(-z) = P[T_{n-1} \leq -z]$ is the cumulative distribution function of T_{n-1} . This yields $z = -\beta$. It follows the interval with confidence level 0.95 is

$$\left[\bar{X}_n + \frac{S_n \beta}{\sqrt{n}}, \bar{X}_n - \frac{S_n \beta}{\sqrt{n}}\right].$$