

## Problem Set #10

EEEC20034 - Introduction to Digital Signal Processing

NYCU

## Problem 1

Suppose that we are given a continuous-time lowpass filter with frequency response  $H_c(j\omega)$  such that

$$\begin{aligned}1 - \delta_1 &\leq |H_c(j\Omega)| \leq 1 + \delta_1, & |\Omega| &\leq \Omega_p, \\ |H_c(j\Omega)| &\leq \delta_2, & |\Omega| &\geq \Omega_s.\end{aligned}$$

A set of discrete-time lowpass filter can be obtained from  $H_c(s)$  by using the bilinear transformation, i.e.,

$$H(z) = H_c(s) \Big|_{s=\left(\frac{2}{T_d}\right) \frac{1-z^{-1}}{1+z^{-1}}},$$

with  $T_d$  variable.

- (a) Assuming that  $\Omega_p$  is fixed, find the value of  $T_d$  such that the corresponding passband cutoff frequency for the discrete-time system is  $\omega_p = \pi/2$ .
- (b) With  $\Omega_p$  fixed, sketch  $\omega_p$  as a function of  $0 < T_d < \infty$ .
- (c) With both  $\Omega_p$  and  $\Omega_s$  fixed, find the expression for the transition region  $\Delta\omega = (\omega_s - \omega_p)$  and sketch the transition region as a function of  $0 < T_d < \infty$ .

## Problem 2 I

A continuous-time filter with impulse response  $h_c(t)$  and frequency-response magnitude

$$|H_c(j\Omega)| = \begin{cases} |\Omega|, & |\Omega| < 10\pi, \\ 0, & |\Omega| > 10\pi, \end{cases}$$

is to be used as the prototype for the design of a discrete-time filter. The resulting discrete-time system is to be used in the configuration of Fig. 3 to filter the continuous-time signal  $x_c(t)$ .

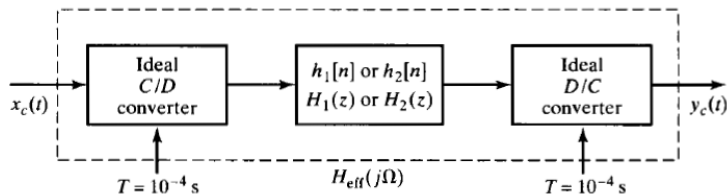


Figure 1

## Problem 2 II

- (a) A discrete-time system with impulse response  $h_1[n]$  and system function  $H_1(z)$  is obtained from the prototype continuous-time system by impulse invariance with  $T_d = 0.01$ ; i.e.,  $h_1[n] = 0.01h_c(0.01n)$ . Plot the magnitude of the overall effective frequency response  $H_{eff}(j\Omega) = Y_c(j\Omega)/X_c(j\Omega)$  when this discrete-time system is used in Fig. 3.
- (b) Alternatively, suppose that a discrete-time system with impulse response  $h_2[n]$  and system function  $H_2(z)$  is obtained from the prototype continuous-time system by the bilinear transformation with  $T_d = 2$ ; i.e.,

$$H_2(z) = H_c(s)|_{s=(1-z^{-1})/(1+z^{-1})},$$

Plot the magnitude of the overall effective frequency response  $H_{eff}(j\Omega)$  when this discrete-time system is used in Fig. 3.