

Improved Detection Performance for Channel Shortening

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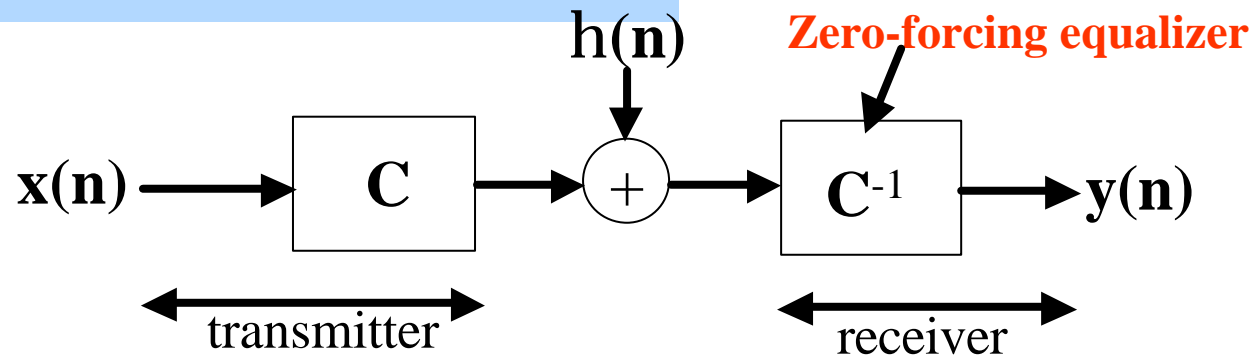
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Channel Shortening and DMT

- Extensively used in Discrete Multitone (DMT) System to minimize ISI and ICI
 - xDSL
 - OFDM
- DMT
 - divide overall channel into multiple subchannels
 - IFFT/FFT used for transmit and receive, respectively
 - no ISI if each subchannel has constant gain and perfect sampling (ideal case)

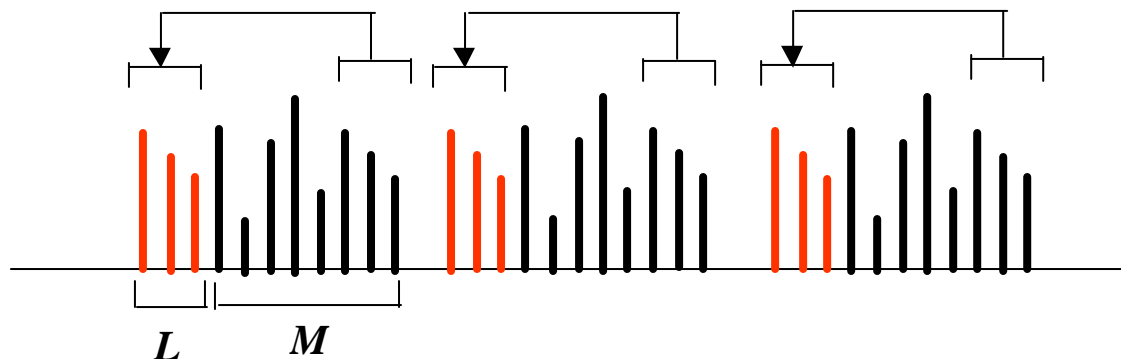
Zero-forcing Equalizer



- Assume FIR model for C
- **Problems:**
 - C has to be minimum phase
 - zeros close to the unit circle in C
 - poles close to unit circle in $C^{-1} \rightarrow$ large noise gain

“Imperfect” Equalization

- Cyclic prefix (CP) is used to minimize ISI and ICI
- Divide input stream into blocks, say of length M
- L symbols at the end of each block is copied to form the CP – periodic sequence
- ISI only affects the L samples in each block



Cyclic Prefix

- **Advantages:**
 - **C** does not have to be minimum phase
 - robust toward channel noise amplification
 - Easy to implement
 - Only need a simple frequency-domain equalizer to cancel magnitude and phase distortion in the remaining M samples
- **Disadvantage:**
 - Decrease transmission efficiency by $M/(M+L)$

DMT System Analysis (1)

- If $L < M$, system can be modeled as:

$$\mathbf{y}(m) = \mathbf{C}\mathbf{x}(m)$$

$$\mathbf{x}(m) = [x(mM) \quad x(mM + 1) \quad \cdots \quad x(mM + M - 1)]^T$$

$$\mathbf{y}(m) = [y(J_m) \quad y(J_m + 1) \quad \cdots \quad y(J_m + M - 1)]^T$$

$$J_m = m(L + M) + L$$

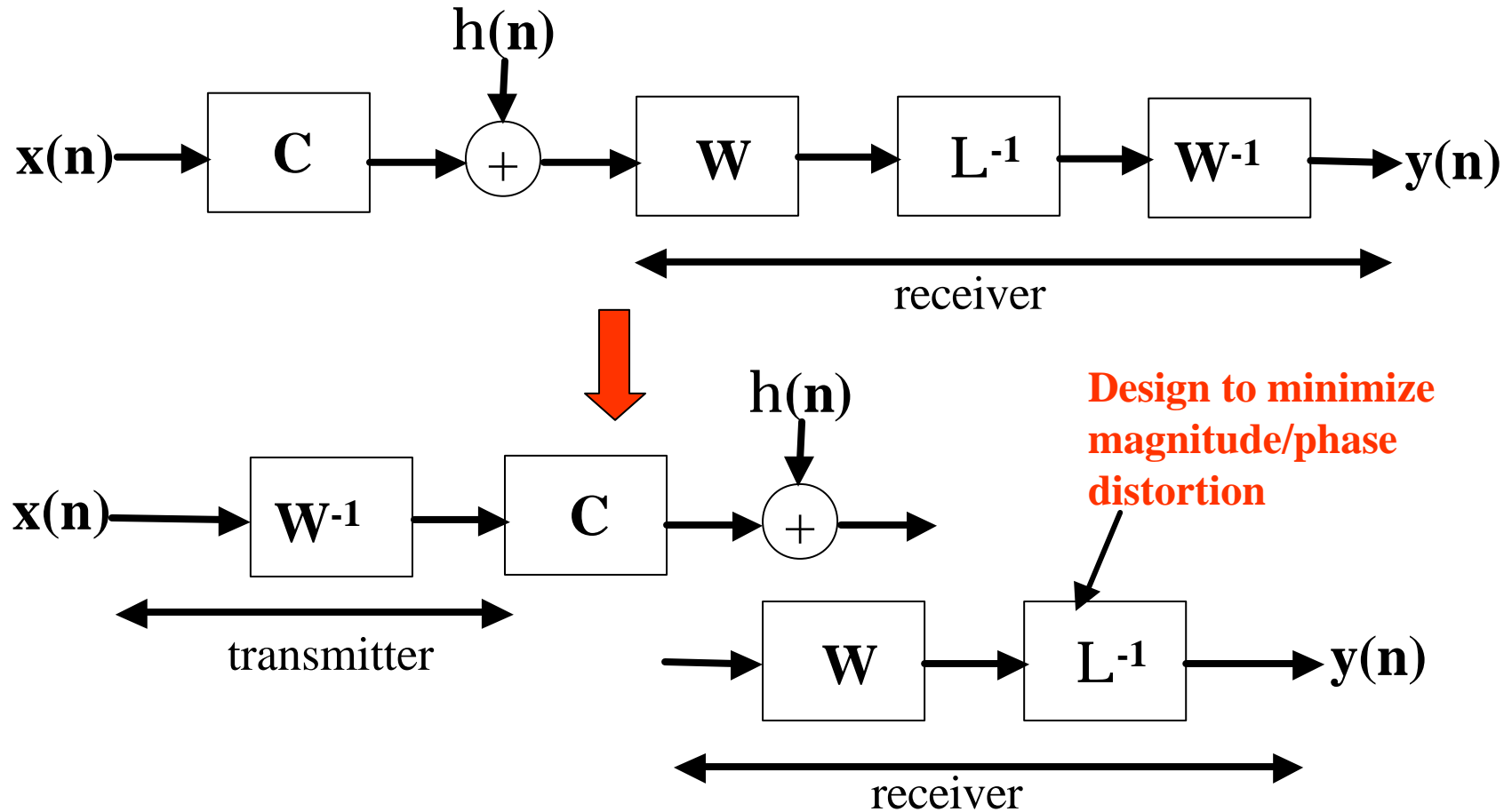
- \mathbf{C} is a circulant matrix of the form ($L=3, M=6$)

$$\mathbf{C} = \begin{bmatrix} c(0) & 0 & 0 & c(3) & c(2) & c(1) \\ c(1) & c(0) & 0 & 0 & c(3) & c(2) \\ c(2) & c(1) & c(0) & 0 & 0 & c(3) \\ c(3) & c(2) & c(1) & c(0) & 0 & 0 \\ 0 & c(3) & c(2) & c(1) & c(0) & 0 \\ 0 & c(4) & c(3) & c(2) & c(1) & c(0) \end{bmatrix}$$

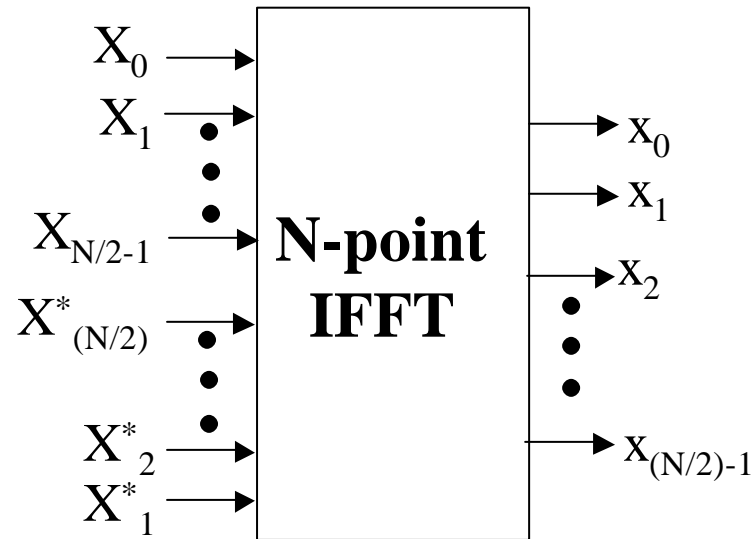
DMT System Analysis (2)

- Can diagonalize the circulant matrix using DFT matrix: $\mathbf{C} = \mathbf{W}^{-1}\mathbf{L}\mathbf{W}$
- Zero-forcing equalizer requires having \mathbf{C}^{-1} at the receiving: $\mathbf{C}^{-1} = \mathbf{W}^{-1}\mathbf{L}^{-1}\mathbf{W}$
- $\mathbf{W}^{-1} = (\mathbf{L}^{-1}\mathbf{W}\mathbf{C})^{-1}$

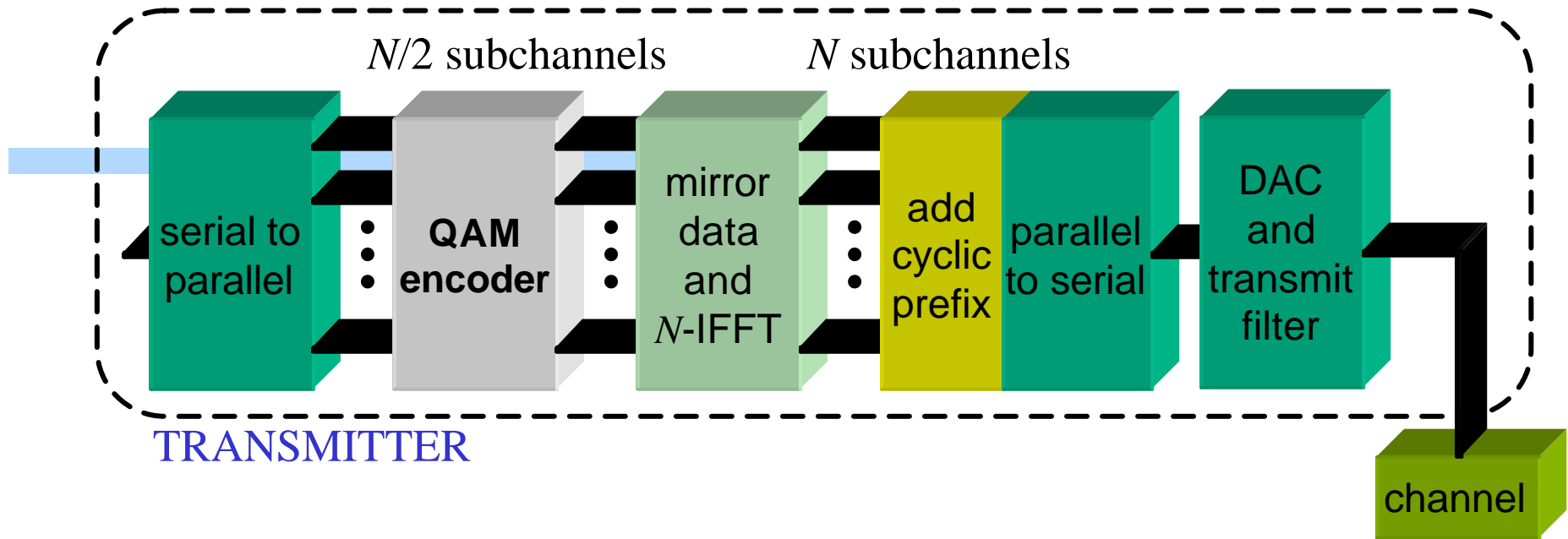
DMT System Analysis (3)



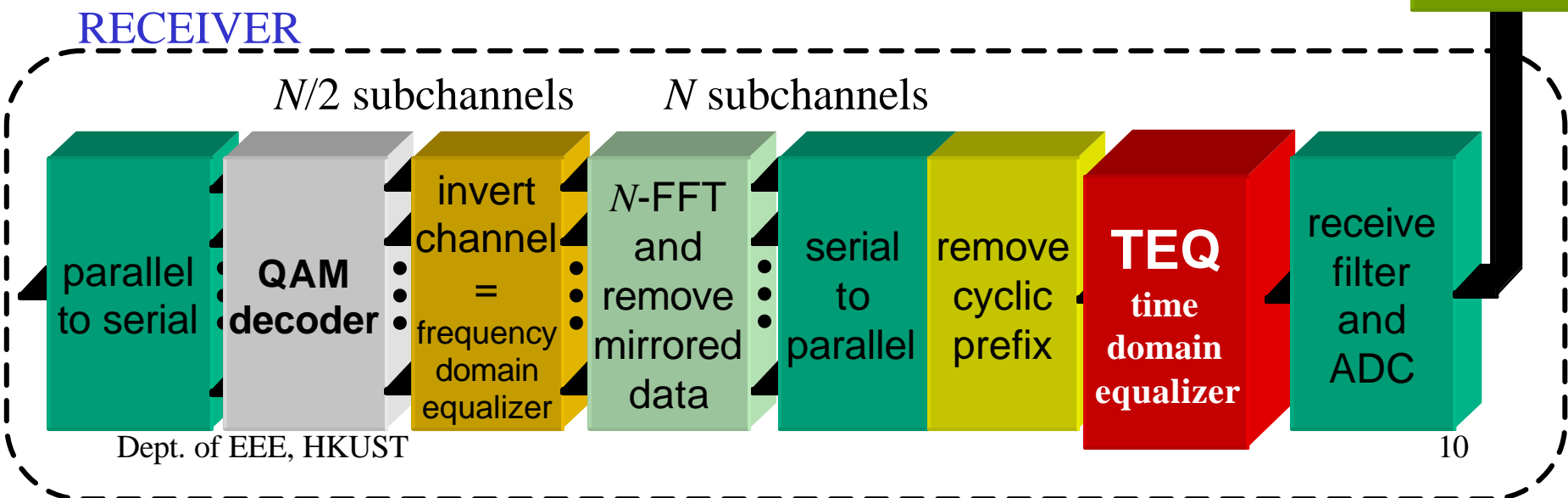
IFFT Transmitter



- N DMT symbols in \rightarrow $N/2$ symbols out
- Ensures real-valued time domain output



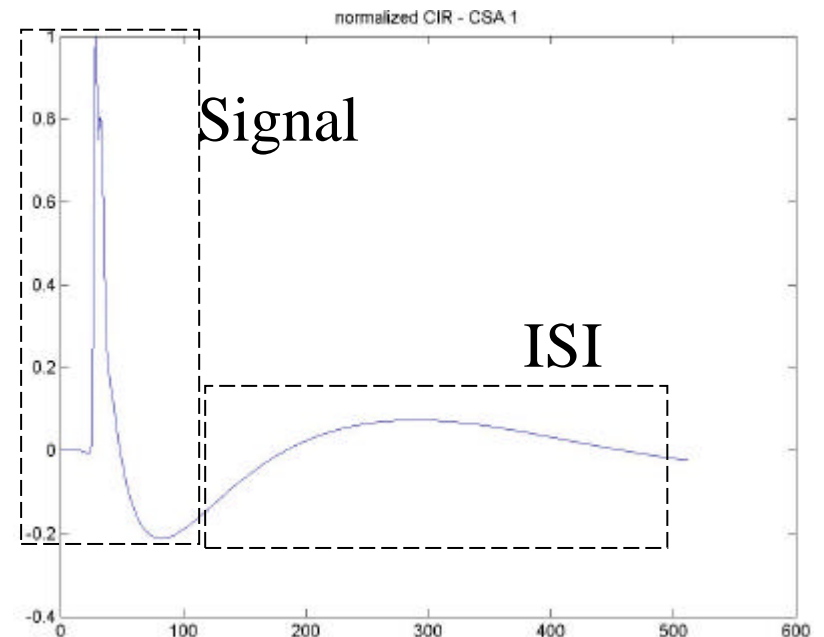
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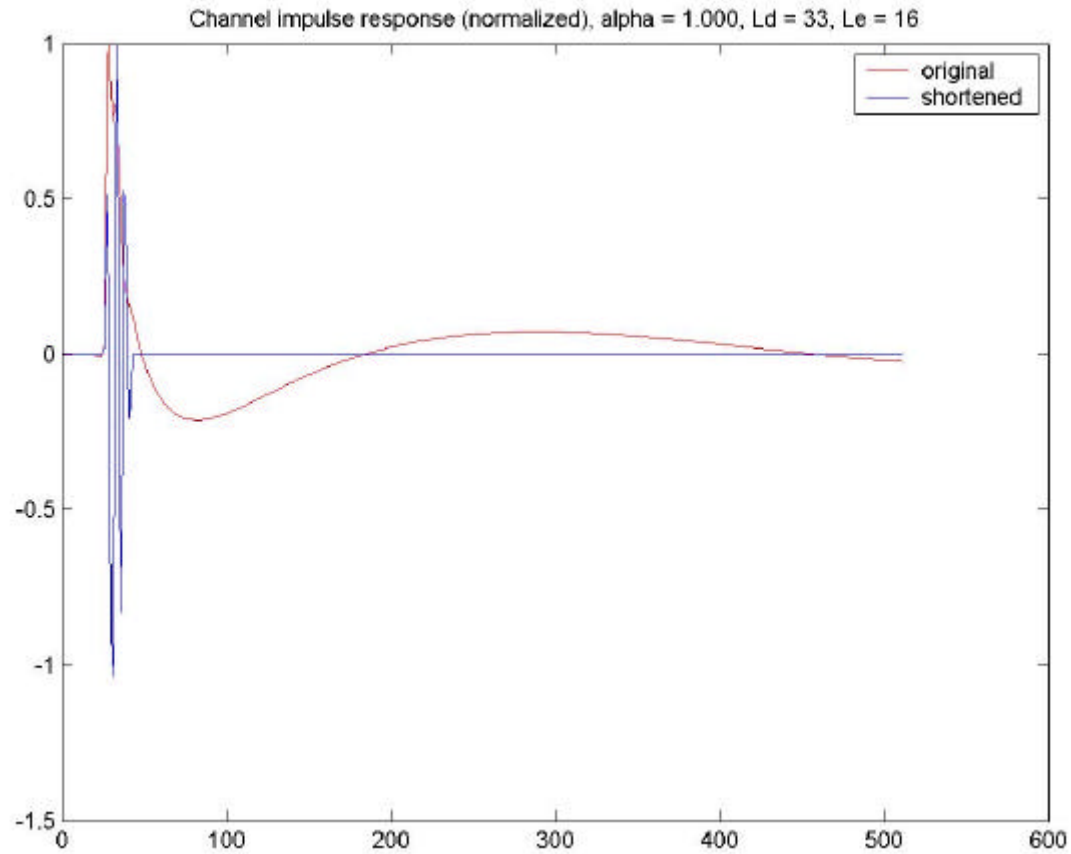
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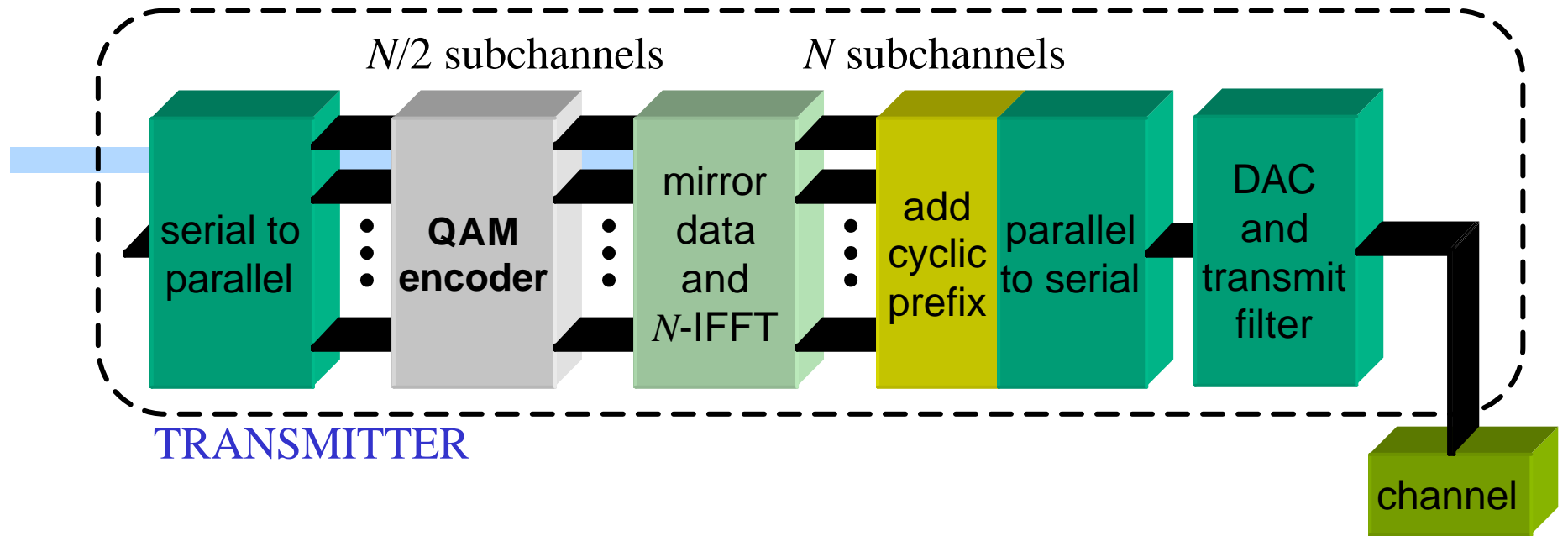
What is Time-Domain Equalizer?

- CP length $\geq L_c + 1$
- L_c shortened \rightarrow CP length shortened \rightarrow higher throughput
- Shorten channel with TEQ
 - window out the undesired portion of the channel
- Some design objectives
 - Minimize ISI power
 - Maximize bit rate
 - Minimize BER



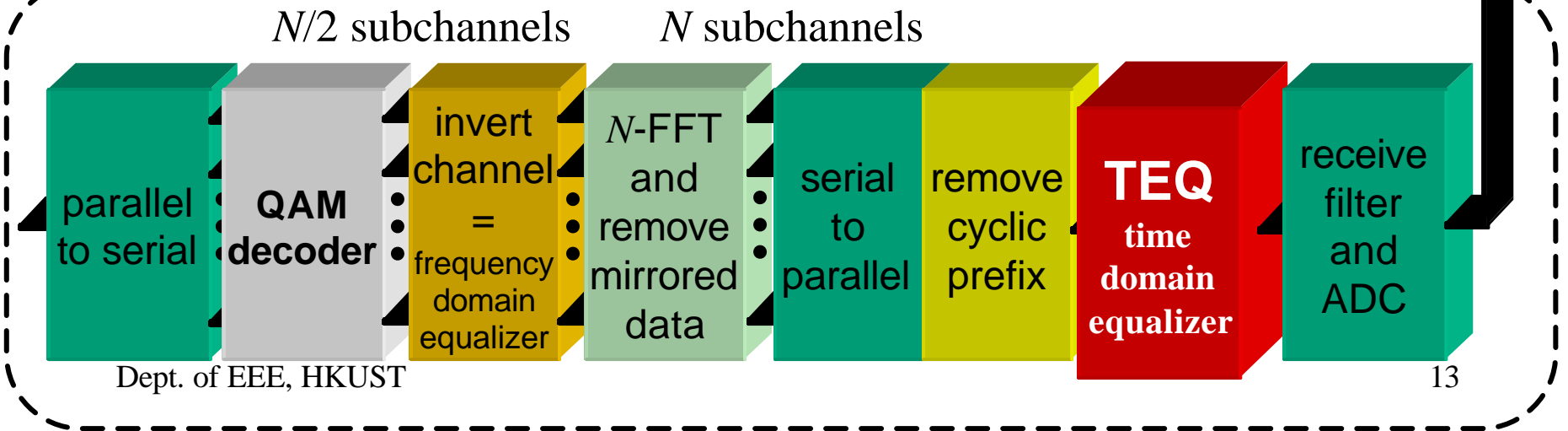
Effect of TEQ





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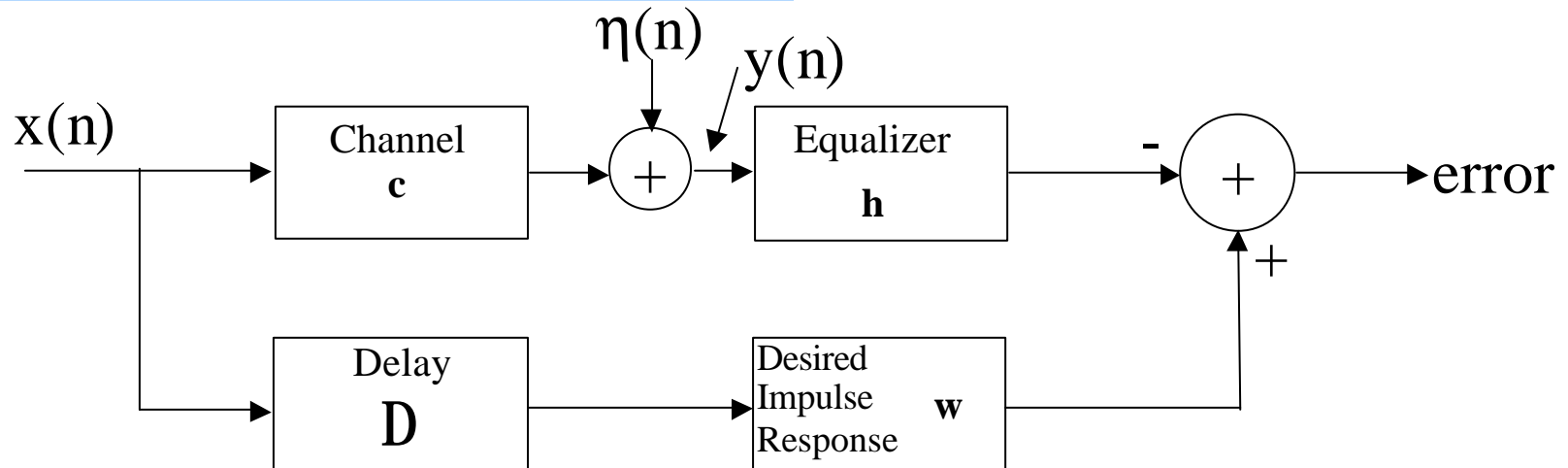
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Past Work

- various TEQ design approach
 - MMSE [*Falconer & Magee, 1973*]
 - Maximize shortening SNR (MSSNR)
 - [*Melsa & et. al., 1996*]
 - [*Wang & et. al., 1999*]
 - Maximize Bit Rate
 - MGSNR [*Al-Dhahir & Cioffi, 1967, Farhang-Boroujeny & Ding, 2001*]
 - MBR [*Arslan, Evans and et. al., 2001*]
 - ISI power/AWGN
 - ISI only [*Schur & Speidel, 2001*]
 - ISI + AWGN [*Tkacenko & Vaidyanathan, 2002*]

MMSE



- MMSE achieved when: $\mathbf{w}^T \mathbf{R}_{xy} = \mathbf{h}^T \mathbf{R}_{yy}$
- **Disadvantages:**
 - don't consider BER
 - don't consider bit rate

MSSNR (1)

- Deal with shortening channel directly
- Idea:
 - ISI lies outside the shortened CIR
 - Maximize/minimize SNR inside/outside TEQ window

$$\begin{aligned}\max_{\mathbf{h}}(\text{SSNR in dB}) &= \max_{\mathbf{h}} 10 \log_{10} \left(\frac{\text{energy inside window after TEQ}}{\text{energy outside window after TEQ}} \right) \\ &= \max_{\mathbf{h}} 10 \log_{10} \frac{\mathbf{c}_{in}^T \mathbf{c}_{in}^T}{\mathbf{c}_{out}^T \mathbf{c}_{out}^T} \\ &= \max_{\mathbf{h}} 10 \log_{10} \frac{\mathbf{h}^T \mathbf{C}_{in}^T \mathbf{C}_{in} \mathbf{h}}{\mathbf{h}^T \mathbf{C}_{out}^T \mathbf{C}_{out} \mathbf{h}} \\ &= \max_{\mathbf{h}} 10 \log_{10} \frac{\mathbf{h}^T \mathbf{B} \mathbf{h}}{\mathbf{h}^T \mathbf{A} \mathbf{h}} \quad \text{s.t. } \mathbf{h}^T \mathbf{B} \mathbf{h} = 1\end{aligned}$$

MSSNR (2)

$$\mathbf{h}_{opt} = \left(\sqrt{\mathbf{B}^T}\right)^{-1} \mathbf{q}_{min} \quad \mathbf{q}_{min} : \text{eigenvector of min eigenvalue of } \mathbf{C}$$

$$\mathbf{C} = \left(\sqrt{\mathbf{B}}\right)^{-1} \mathbf{A} \left(\sqrt{\mathbf{B}^T}\right)^{-1}$$

- **Disadvantages:**

- leakage effect of FFT subbands not taken care of
- doesn't account for additive noise

Maximize Bit Rate

- Bit rate expression:

$$b_{DMT} = \sum_{i=1}^{N/2} \log_2 \left(1 + \frac{SNR_i}{\Gamma_i} \right) \quad \text{bits/symbol}$$

i : subchannel index

SNR_i : SNR in the i^{th} subchannel

Γ : $\Gamma(P_e, C)$ - SNR gap for achieving Shannon channel capacity
 C - line code, function of basis function (modulation)
and signal constellation

MGSNR (1)

- Maximize geometric SNR (MGSNR)
 - replace SNR with GSNR

$$GSNR \equiv \Gamma \left[\left(\prod_{i=1}^N \left(1 + \frac{SNR_i}{\Gamma} \right) \right)^{\frac{2}{N}} - 1 \right]$$
$$\approx \left[\prod_{i=1}^N SNR_i \right]^{\frac{2}{N}}$$

- Assume: $\Gamma_i = \Gamma$ (assume same P_e for all subchannel s)
 $SNR_i = \frac{S_x |H_i|^2}{R_{n,i}}$ (assume flat input energy across subchannel s)

$$\Rightarrow b_{DMT} = \frac{N}{2} \log_2 \left(1 + \frac{GSNR}{\Gamma} \right)$$

MGSNR (2)

- Maximize bit rate becomes maximizing the GSNR
- **Disadvantage:** cannot achieve optimal solution (as shown in MBR)
 - too much assumptions and approximations in GSNR expression
 - does not include ISI power

MBR (1)

- Works with original b_{DMT} expression with

$$SNR_i = \frac{\text{signal power}}{\text{additive noise power} + \text{ISI power}}$$

- SNR_i expression that includes ISI power
- assume $\Gamma_i = \Gamma$ only
- achieve near optimal solution for achievable bit rate

$$b_{DMT} = \sum_{i=1}^{N/2} \log_2 \left(1 + \frac{1}{\Gamma} \frac{\mathbf{h}^T \mathbf{A}_i \mathbf{h}}{\mathbf{h}^T \mathbf{B}_i \mathbf{h}} \right)$$

\mathbf{A} : signal power inside window

\mathbf{B} : signal power outside window + additive noise power

MBR (2)

- **Disadvantages:**
 - High BER (compared to our design)
 - Requires nonlinear optimization

Eigenfilter TEQ (1)

- Trade-off between additive noise and ISI power to allow more design freedom
- Able to get a global optimal using Rayleigh quotient

$$\begin{aligned} J &= \frac{\mathbf{a}(\text{ISI power}) + (1 - \mathbf{a})(\text{additive noise power})}{\text{signal power}} \\ &= \frac{\mathbf{a} \mathbf{s}_{x_{res}}^2 + (1 - \mathbf{a}) \mathbf{s}_q^2}{\mathbf{s}_{x_{des}}^2} \\ \Rightarrow J &= \min_{\mathbf{v}} \frac{\mathbf{v}^H \mathbf{T} \mathbf{v}}{\mathbf{v}^H \mathbf{v}} \end{aligned}$$

EIGFILT (2)

- **Disadvantage:**
 - high BER (compared to our design)
 - does not account for the bit rate

Can we do better on BER?

- ISI taken care of by the CP
- Minimize the channel noise → minimize the BER
 - fixed ISI noise as a constraint
- Exact computation of BER not available analytically
 - Minimize a tight bound instead → Chernoff bound
- Chernoff bound of Q -function

$$P_e \equiv \frac{2}{N} \sum_{i=1}^{N/2} Q\left(\sqrt{k_m SNIR_i}\right)$$

$$Q\left(\sqrt{k_m SNIR_i}\right) \leq \exp\left(-\frac{k_m SNIR_i}{2}\right)$$

Chernoff TEQ design

$$SNIR_i = \frac{\mathbf{s}_x^2 \mathbf{h} \mathbf{C} \mathbf{W}_\Delta \mathbf{C}^H \mathbf{h}^H}{\mathbf{s}_x^2 \mathbf{h} \mathbf{C} \overline{\mathbf{W}}_\Delta \mathbf{C}^H \mathbf{h}^H + \mathbf{h} \mathbf{R}_h \mathbf{h}^H}$$

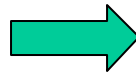
$$J = \min_{\mathbf{h}} \exp \left(- \frac{\mathbf{s}_x^2 \mathbf{h} \mathbf{C} \mathbf{W}_\Delta \mathbf{C}^H \mathbf{h}^H}{2(\mathbf{s}_x^2 \mathbf{h} \mathbf{C} \overline{\mathbf{W}}_\Delta \mathbf{C}^H \mathbf{h}^H + \mathbf{h} \mathbf{R}_h \mathbf{h}^H)} \right)$$

$$\text{s.t. } \mathbf{h} \mathbf{C} \mathbf{W}_\Delta \mathbf{C}^H \mathbf{h}^H = m \mathbf{c}^H = m E_c$$

$$\text{since } \overline{\mathbf{W}}_\Delta = \mathbf{I} - \mathbf{W}_\Delta$$

$$J = \min_{\mathbf{h}} \mathbf{h} (\mathbf{C} \mathbf{C}^H + \mathbf{s}_x^{-2} \mathbf{R}) \mathbf{h}^H$$

$$\text{s.t. } \mathbf{h} \mathbf{C} \mathbf{W}_\Delta \mathbf{C}^H \mathbf{h}^H = m E_c$$



$$J = \min_{\mathbf{h}} \mathbf{h} \mathbf{P} \mathbf{h}^H$$

$$\text{s.t. } \mathbf{h} \mathbf{Q} \mathbf{h}^H = m E_c$$

Notations

$$\mathbf{h} \equiv [h(0) \ h(1) \ \dots \ h(L_e - 1)]$$

$$\mathbf{c} \equiv [c(0) \ c(1) \ \dots \ c(L_c - 1)]$$

$$\mathbf{C} \equiv \begin{bmatrix} c(0) & c(1) & \dots & c(L_c - 1) & 0 & \dots & 0 \\ 0 & c(0) & c(1) & \dots & c(L_c - 1) & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \ddots & \ddots & 0 \\ 0 & \dots & 0 & c(0) & c(1) & \dots & c(L_c - 1) \end{bmatrix}$$

$$\mathbf{W}_\Delta \equiv \begin{bmatrix} \mathbf{0}_\Delta & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{I}_{L_d} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{0}_{L_c + L_e - L_d - 1 - \Delta} \end{bmatrix}$$

Δ : delay

L_e : Equalizer length

L_c : Channel length

L_d : Desired effective/shortened channel length

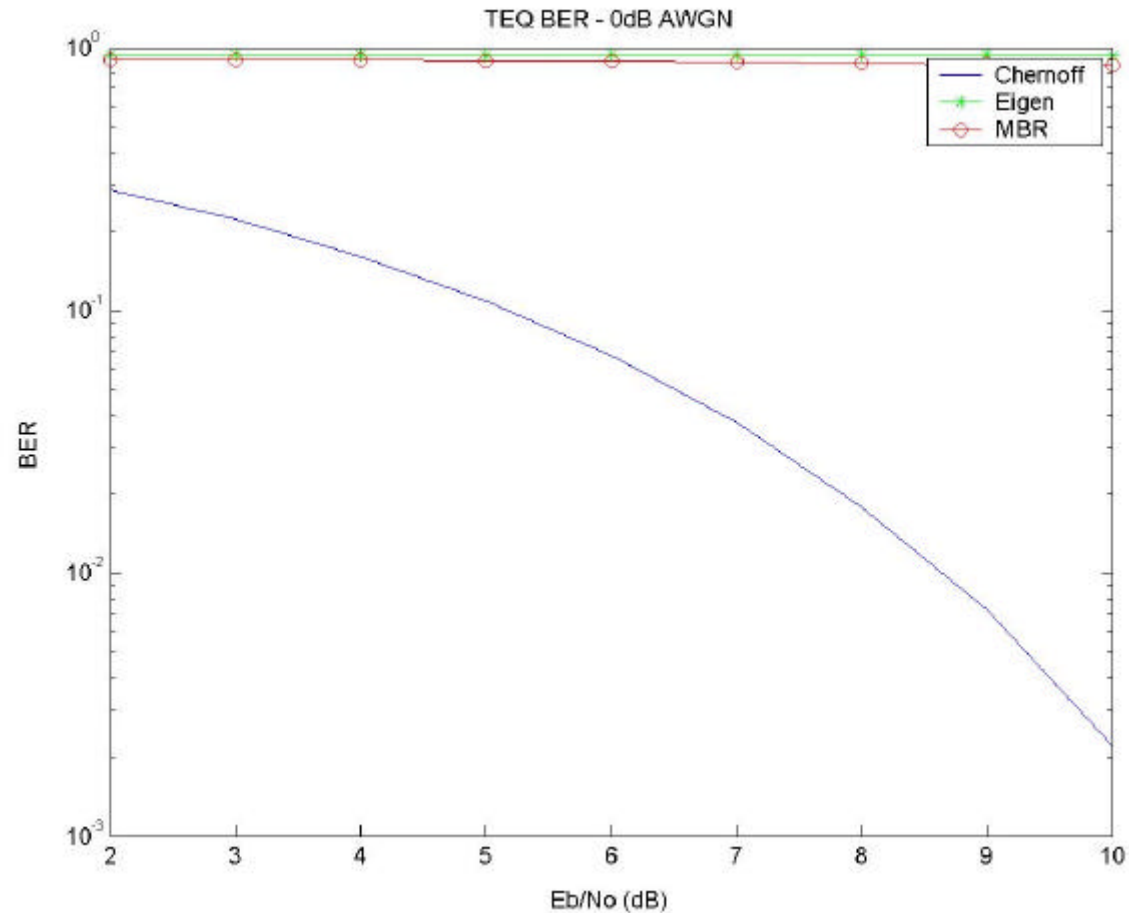
Comparison

- Chernoff (Fung & Kok, 2003)
 - minimize BER
- EIGFILT (Tkacenko & Vaidyanathan, 2002)
 - minimize ISI power/additive noise power
- MBR (Arslans, Evans & et. al., 2001)
 - maximize bit rate

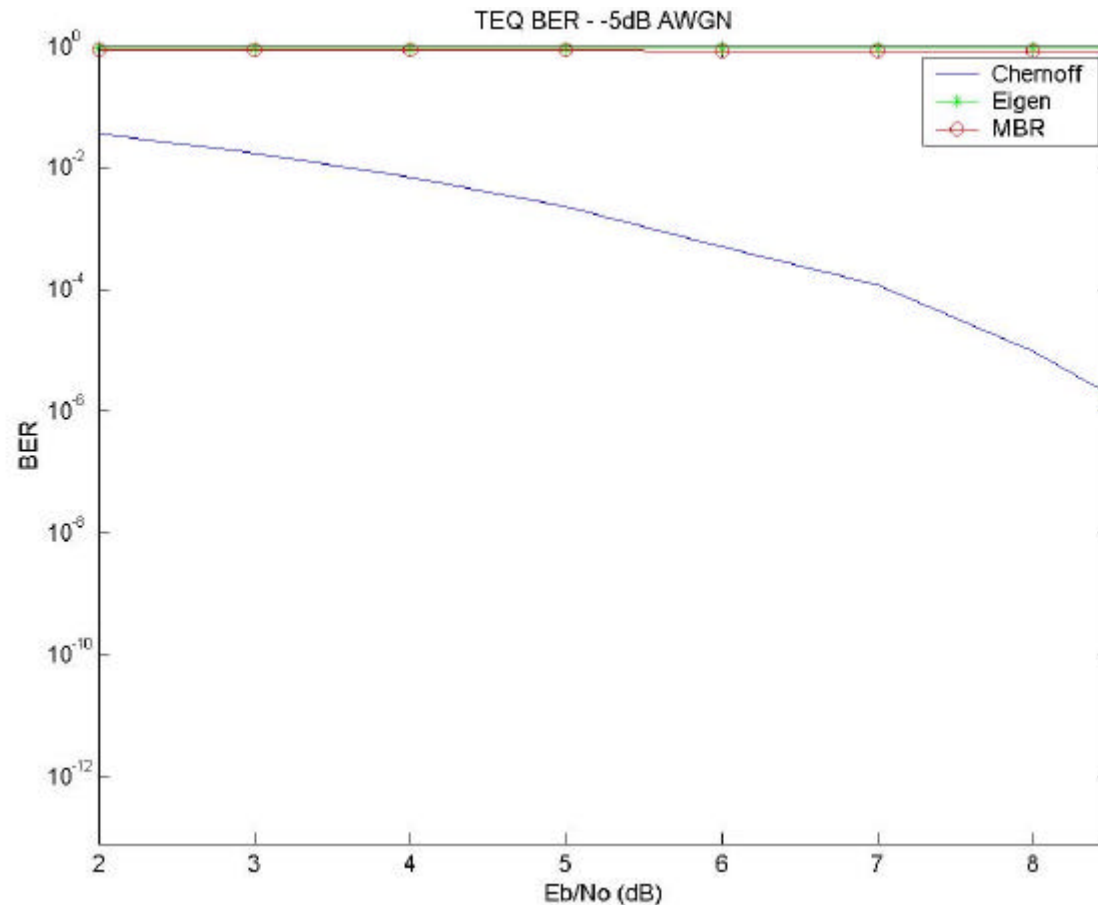
Design Parameters

Input signal power	14 dBm
AWGN power	-110 dBm
Length of equalizer	16 – 45 taps
Desired length of effective channel	33/48
Delay of effective channel	10 (Chernoff and EIGFILT)
Channel	CSA loop 1, 2, 6
Channel length	512
Size of DFT	512
Sampling frequency	2.208 MHz
μ	0.5 – 0.95

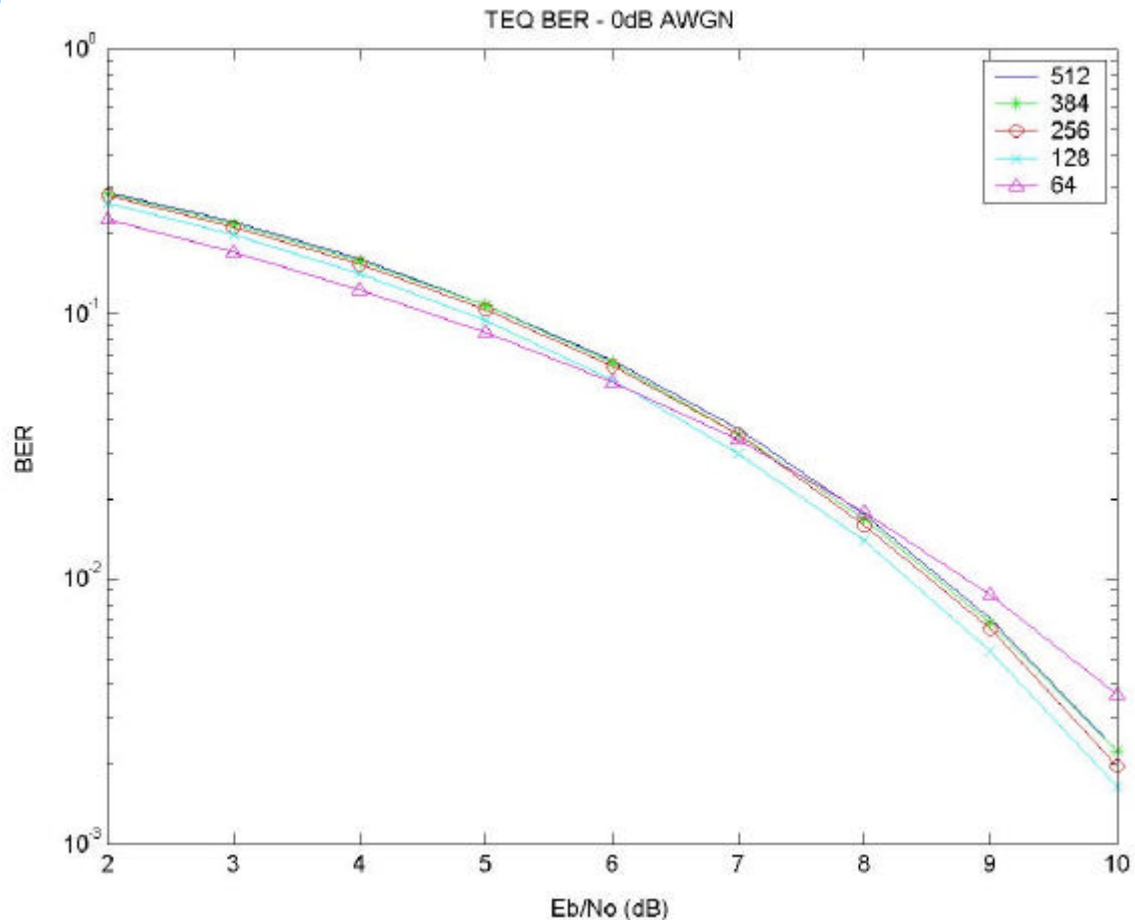
Results - different TEQs (1)



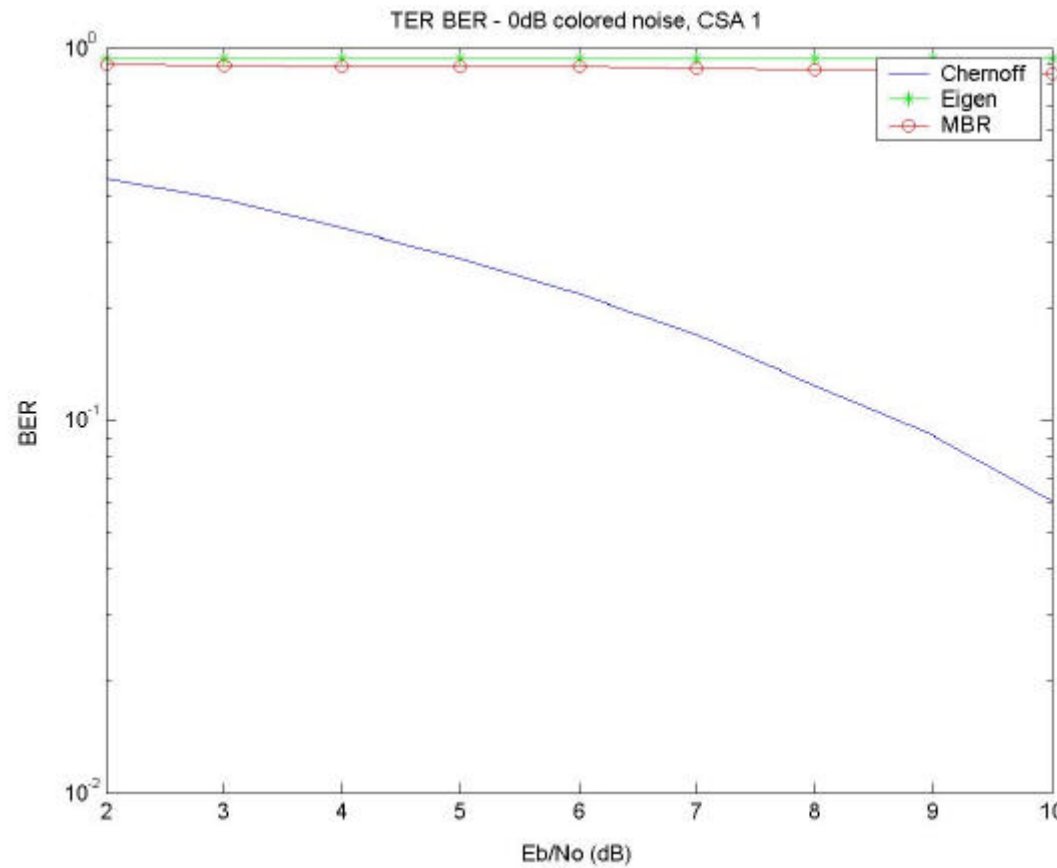
Results - different TEQs (2)



Robustness - different channel lengths



Robustness - colored noise



Conclusion

- BER optimized TEQ design
- Better BER than EIGENFILT and MBR
- Robustness:
 - different channel length
 - colored noise
- Closed form expression?
 - Iterative solution possible
- Further investigation on the effect of μ
- Can we incorporate both objectives?
 - Maximize bit rate
 - Minimize BER

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